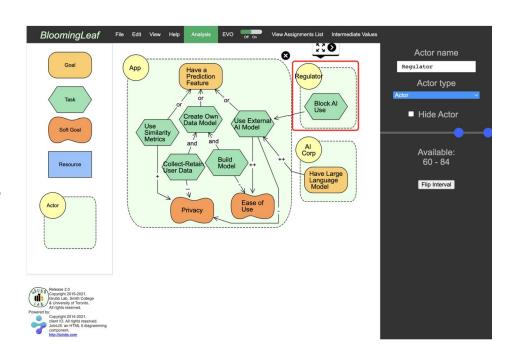
# Incorporating **Presence Conditions** into Goal Models that Evolve Over Time

Xinran Bi and Alicia M. Grubb Smith College, United States

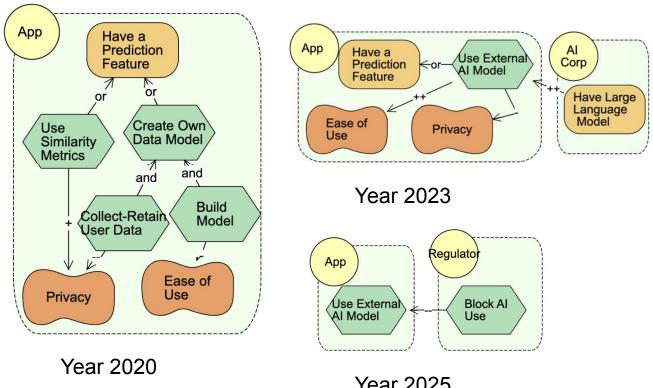






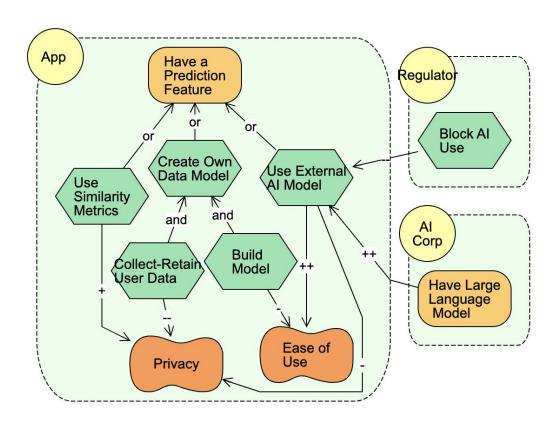
September 5, 2023 Model-Driven Requirements Engineering Workshop (MoDRE)

# Why presence conditions? Example of the Predictive App

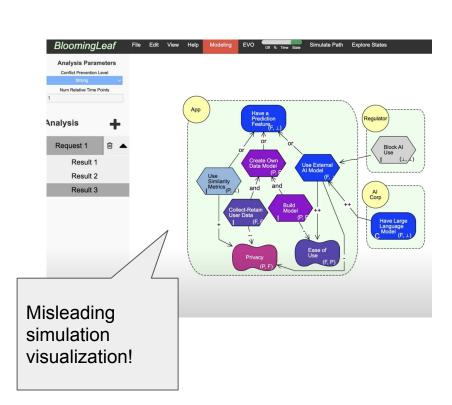


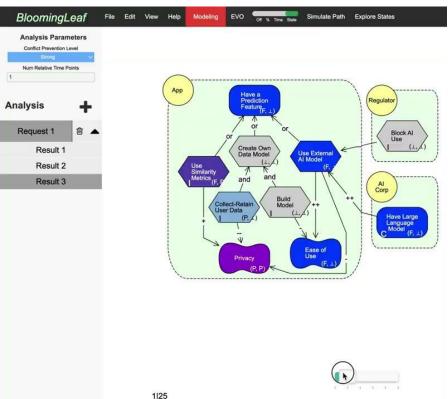
Year 2025

# Why presence conditions? Example of the Predictive App



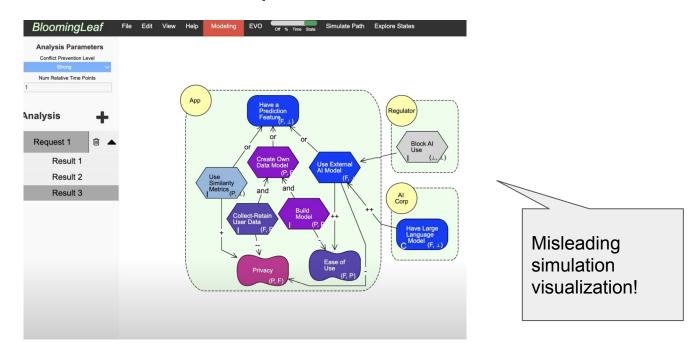
## Simulation without presence conditions



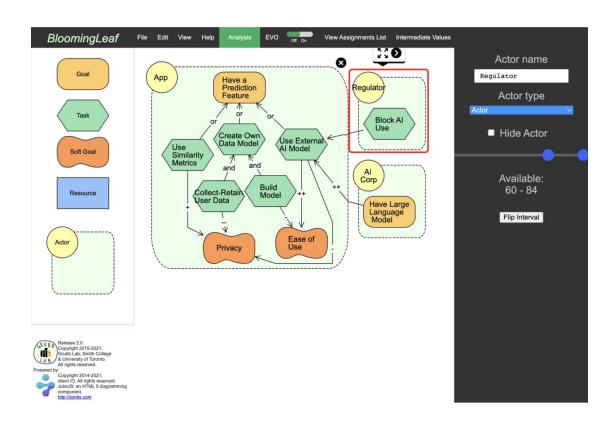


### Research Problem:

**Avoid nonsensical visualization** after merging model segments from different time points

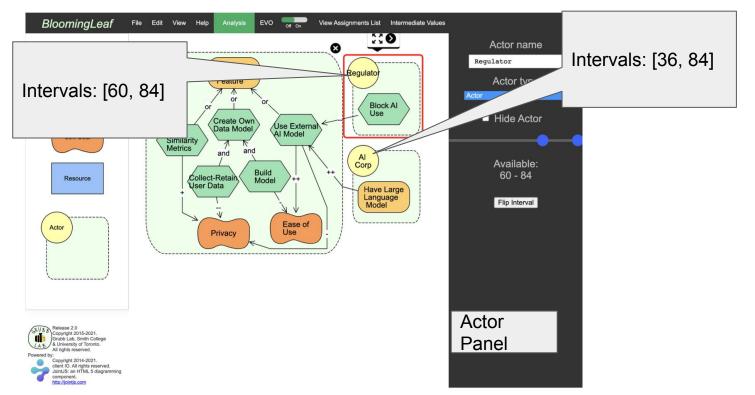


### Our contribution

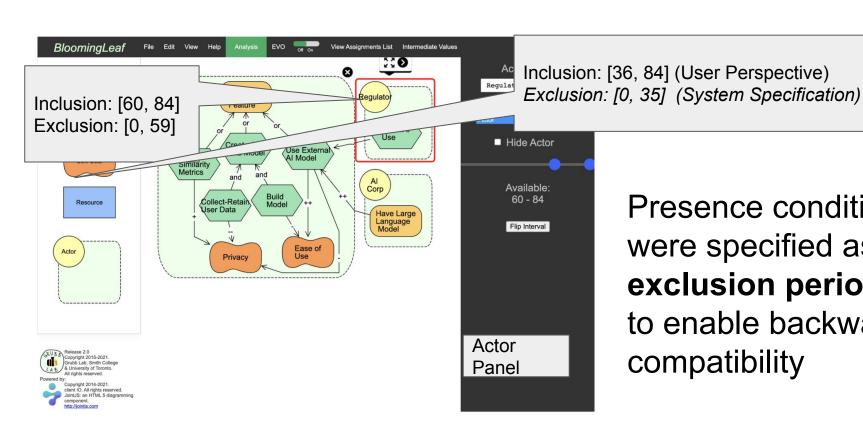


Incorporated presence conditions into the Evolving Intentions framework to avoid nonsensical visualization

# Presences conditions are implemented as part of BloomingLeaf in the front-end actor



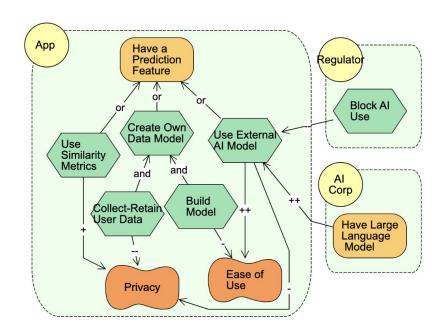
# Presence conditions specifications



Presence conditions were specified as exclusion periods to enable backward compatibility

## Presence conditions specifications - Actor

actor  $a \in A$ :  $\langle name, type, intention-set, exclusion-set (optional) \rangle$ 



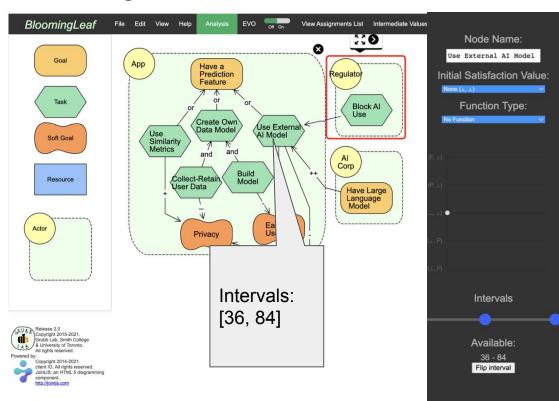
Inclusion: [0, 84], 84 is Maximum absolute time

Exclusion: []

Inclusion: *User perspective* 

Exclusion: System specification

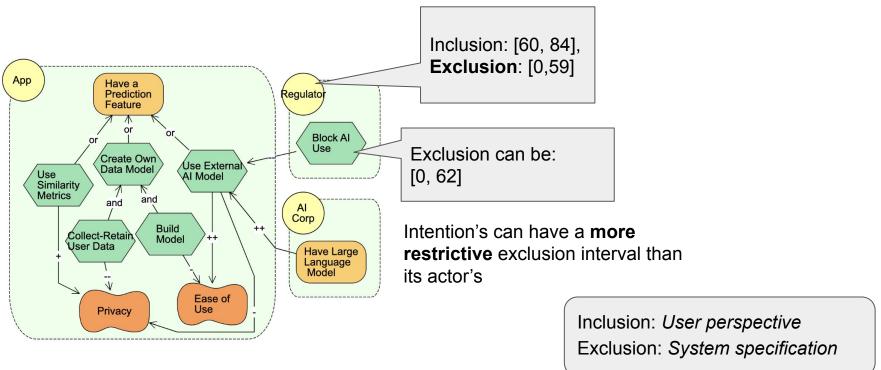
# Presences conditions are implemented as part of BloomingLeaf in the front-end intention



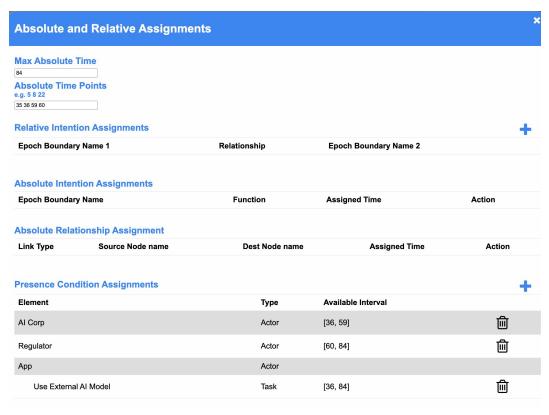
Intention Panel

## Presence conditions specifications - Intention

intention  $g \in G$ :  $\langle name, type, intention-set, exclusion-set (optional) \rangle$ 

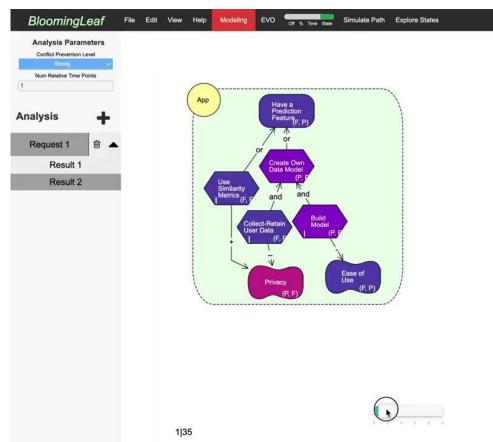


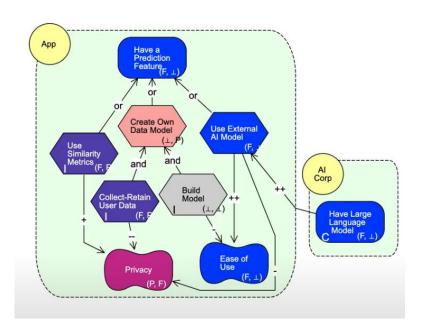
# Model-level view of presence conditions assignment



Help user keep track of every elements' presence conditions specification

### Simulation with Presence Conditions



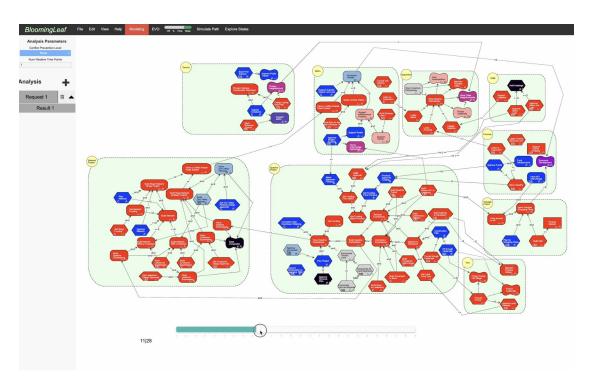


Has a better representation of when does certain actors come into play

# Evaluation - Our approach is scalable, tested by a model over 100 intentions

Model of a large road construction project\*

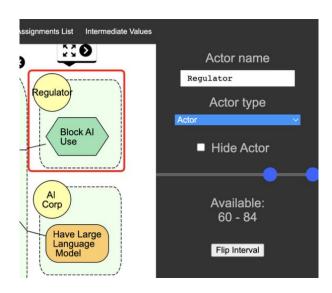
Can be improved by allowing to select multiple intentions at one time



<sup>\*</sup> A.M. Grubb and M. Chechik. Reconstructing the Past: The Case of the Spadina Expressway. Requirements Engineering (**REJ**), 25(2):253–272, 2020.

# Model slicing

Using presence conditions as model slices allows us to empirically observe how stakeholders interpret large models.



Similar 'Hide' function in the analysis mode Allow us to study how users explore large models

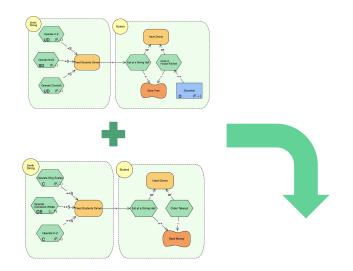
# Ongoing Work & Future Work

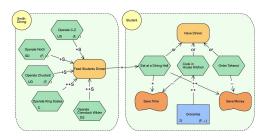
#### Next steps:

Improve backend analysis to take presence conditions into account

Incorporate presence conditions with model merging and slicing

Generalizing our approach to other goal modeling languages





#### Related Work

Used for specifying software product lines in model-driven engineering

- Software product lines variability
- Domain Specific Languages (DSLs) for mapping feature models

#### Goal modeling:

TimeURN

While we specify presence conditions as **temporal ranges**, not boolean conditions

## Summary

We extended the Evolving Intentions framework to enable analysts to specify presence conditions

We integrated this extension in one of the goal modeling tools, BloomingLeaf

#### Acknowledgements:

We thank the members of our lab who helped in tool development and gave us feedback on this project: Venus Nguyen, Emily Kung, Karenna Kung, Thu Tran, and Caroline Zouloumian

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